### CLASS - 12

### CHAPTER -11 Three Dimensional Geometry

**Direction Cosines of a Line:** If the directed line OP makes angles  $\alpha$ ,  $\beta$ , and  $\gamma$  with positive X-axis, Y-axis and Z-axis respectively, then  $\cos \alpha$ ,  $\cos \beta$ , and  $\cos \gamma$ , are called direction cosines of a line. They are denoted by I, m, and n. Therefore, I =  $\cos \alpha$ , m =  $\cos \beta$  and n =  $\cos \gamma$ . Also, sum of squares of direction cosines of a line is always 1,

i.e.  $l^2 + m^2 + n^2 = 1$  or  $cos^2 \alpha + cos^2 \beta + cos^2 \gamma = 1$ 

Note: Direction cosines of a directed line are unique.

**Direction Ratios of a Line:** Number proportional to the direction cosines of a line, are called direction ratios of a line.

(i) If a, b and c are direction ratios of a line, then l/a = m/b = n/c

(ii) If a, b and care direction ratios of a line, then its direction cosines are

$$l = \pm \frac{a}{\sqrt{a^2 + b^2 + c^2}}, m = \pm \frac{b}{\sqrt{a^2 + b^2 + c^2}}, n = \pm \frac{c}{\sqrt{a^2 + b^2 + c^2}}$$

(iii) Direction ratios of a line PQ passing through the points  $P(x_1, y_1, z_1)$  and  $Q(x_2, y_2, z_2)$  are  $x_2 - x_1$ ,  $y_2 - y_1$  and  $z_2 - z_1$  and direction cosines are

$$\frac{x_2 - x_1}{|\overrightarrow{PQ}|},$$

$$\frac{y_2 - y_1}{|\overrightarrow{PQ}|}, \frac{z_2 - z_1}{|\overrightarrow{PQ}|}.$$

Note:

(i) Direction ratios of two parallel lines are proportional.

(ii) Direction ratios of a line are not unique.

**Straight line:** A straight line is a curve, such that all the points on the line segment joining any two points of it lies on it.

Equation of a Line through a Given Point and parallel to a given vector  $\vec{b}$ Vector form  $\vec{r} = \vec{a} + \lambda \vec{b}$  where,  $\vec{a} = Position$  vector of a point through which the line is passing  $\vec{b} = A$  vector parallel to a given line

Cartesian form

 $\frac{x-x_1}{a} = \frac{y-y_1}{b} = \frac{z-z_1}{c}$ 

where,  $(x_1, y_1, z_1)$  is the point through which the line is passing through and a, b, c are the direction ratios of the line.

If I, m, and n are the direction cosines of the line, then the equation of the line is

 $\frac{x-x_1}{l} = \frac{y-y_1}{m} = \frac{z-z_1}{n}.$ 

Remember point: Before we use the DR's of a line, first we have to ensure that coefficients of x, y and z are unity with a positive sign.

### **Equation of Line Passing through Two Given Points**

**Vector form:**  $\vec{r} = \vec{a} + \lambda(\vec{b} - \vec{a}), \lambda \in \mathbb{R}$ , where a and b are the position vectors of the points through which the line is passing.

### **Cartesian form**

$$\frac{x - x_1}{x_2 - x_1} = \frac{y - y_1}{y_2 - y_1} = \frac{z - z_1}{z_2 - z_1}$$

where,  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$  are the points through which the line is passing.

### Angle between Two Lines

**Vector form:** Angle between the lines  $\vec{r} = a1 \rightarrow +\lambda b1 \rightarrow and \vec{r} = a2 \rightarrow +\mu b2 \rightarrow is$  given as

$$\cos\theta = \begin{vmatrix} \overrightarrow{b_1 \cdot b_2} \\ \overrightarrow{b_1 | \cdot | b_2} \end{vmatrix}$$

Cartesian form If 
$$\theta$$
 is the angle between the lines  $\frac{x - x_1}{a_1} = \frac{y - y_1}{b_1} = \frac{z - z_1}{c_1}$  and  $\frac{x - x_2}{a_2} = \frac{y - y_2}{b_2} = \frac{z - z_2}{c_2}$ , then  $\cos \theta = \left| \frac{a_1 a_2 + b_1 b_2 + c_1 c_2}{\sqrt{a_1^2 + b_1^2 + c_1^2} \cdot \sqrt{a_2^2 + b_2^2 + c_2^2}} \right|$   
or  $\sin \theta = \frac{\sqrt{(a_1 b_2 - a_2 b_1)^2 + (b_1 c_2 - b_2 c_1)^2 + (c_1 a_2 - c_2 a_1)^2}}{\sqrt{a_1^2 + b_1^2 + c_1^2} \cdot \sqrt{a_2^2 + b_2^2 + c_2^2}}$ 

Also, angle ( $\theta$ ) between two lines with direction cosines,  $l_1, m_1, n_1$  and  $l_2, m_2, n_2$  is given by  $\cos \theta = l_1 l_2 + m_1 m_2 + n_1 n_2$ 

or 
$$\sin\theta = \sqrt{(m_1n_2 - m_2n_1)^2 + (n_1l_2 - n_2l_1)^2 + (l_1m_2 - l_2m_1)^2}$$

**Condition of Perpendicularity:** Two lines are said to be perpendicular, when in vector form  $b1 \rightarrow b2 \rightarrow =0$ ; in cartesian form  $a_1a_2 + b_1b_2 + c_1c_2 = 0$ 

or  $I_1I_2 + m_1m_2 + n_1n_2 = 0$  [direction cosine form]

**Condition that Two Lines are Parallel:** Two lines are parallel, when in vector form  $b1 \rightarrow b2 \rightarrow = |||b1 \rightarrow ||||||b2 \rightarrow |||$ ; in cartesian form a1/a2=b1/b2=c1/c2 or |1/l2=m1/m2=n1/n2 [direction cosine form]

**Shortest Distance between Two Lines:** Two non-parallel and non-intersecting straight lines, are called skew lines.

For skew lines, the line of the shortest distance will be perpendicular to both the lines.

**Vector form:** If the lines are  $\vec{r} = a1 \rightarrow +\lambda b1 \rightarrow and \vec{r} = a2 \rightarrow +\lambda b2 \rightarrow$ . Then, shortest distance

$$d = \left| \frac{(\overrightarrow{b_1} \times \overrightarrow{b_2}) \cdot (\overrightarrow{a_2} - \overrightarrow{a_1})}{|\overrightarrow{b_1} \times \overrightarrow{b_2}|} \right|$$

where  $a2 \rightarrow$ ,  $a1 \rightarrow$  are position vectors of point through which the line is passing and  $b1 \rightarrow$ ,  $b2 \rightarrow$  are the vectors in the direction of a line.

Cartesian form: If the lines are

$$\frac{x-x_1}{a_1} = \frac{y-y_1}{b_1} = \frac{z-z_1}{c_1} \text{ and } \frac{x-x_2}{a_2} = \frac{y-y_2}{b_2} = \frac{z-z_2}{c_2}.$$

Then, shortest distance,

$$d = \begin{vmatrix} x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix}$$
$$\frac{1}{\sqrt{(b_1c_2 - b_2c_1)^2 + (c_1a_2 - c_2a_1)^2 + (a_1b_2 - a_2b_1)^2}}$$

**Distance between two Parallel Lines:** If two lines  $l_1$  and  $l_2$  are parallel, then they are coplanar. Let the lines be  $\vec{r} = a1 \rightarrow +\lambda \vec{b}$  and  $\vec{r} = a2 \rightarrow +\mu \vec{b}$ , then the distance between parallel lines is

$$\frac{\overrightarrow{b} \times (\overrightarrow{a_2} - \overrightarrow{a_1})}{\overrightarrow{b}}$$

Note: If two lines are parallel, then they both have same DR's.

**Distance between Two Points:** The distance between two points P ( $x_1$ ,  $y_1$ ,  $z_1$ ) and Q ( $x_2$ ,  $y_2$ ,  $z_2$ ) is given by

$$PQ = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

**Mid-point of a Line:** The mid-point of a line joining points A  $(x_1, y_1, z_1)$  and B  $(x_2, y_2, z_2)$  is given by

$$\left(\frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2}, \frac{z_1 + z_2}{2}\right)$$

**Plane:** A plane is a surface such that a line segment joining any two points of it lies wholly on it. A straight line which is perpendicular to every line lying on a plane is called a normal to the plane.

### Equations of a Plane in Normal form

**Vector form:** The equation of plane in normal form is given by  $\vec{r} \cdot \vec{n} = d$ , where  $\vec{n}$  is a vector which is normal to the plane.

**Cartesian form:** The equation of the plane is given by ax + by + cz = d, where a, b and c are the direction ratios of plane and d is the distance of the plane from origin.

Another equation of the plane is lx + my + nz = p, where l, m, and n are direction cosines of the perpendicular from origin and p is a distance of a plane from origin.

Note: If d is the distance from the origin and l, m and n are the direction cosines of the normal to the plane through the origin, then the foot of the perpendicular is (ld, md, nd).

# Equation of a Plane Perpendicular to a given Vector and Passing Through a given Point

**Vector form:** Let a plane passes through a point A with position vector  $\vec{a}$  and perpendicular to the vector  $\vec{n}$ , then  $(\vec{r} - \vec{a}) \cdot \vec{n} = 0$ 

This is the vector equation of the plane.

**Cartesian form:** Equation of plane passing through point  $(x_1, y_1, z_1)$  is given by a  $(x - x_1) + b (y - y_1) + c (z - z_1) = 0$  where, a, b and c are the direction ratios of normal to the plane.

### **Equation of Plane Passing through Three Non-collinear Points**

**Vector form:** If  $\vec{a}$ ,  $\vec{b}$  and  $\vec{c}$  are the position vectors of three given points, then equation of a plane passing through three non-collinear points is  $(\vec{r} - \vec{a}) \cdot \{(\vec{b} - \vec{a}) \times (\vec{c} - \vec{a})\}=0$ .

**Cartesian form:** If  $(x_1, y_1, z_1)$   $(x_2, y_2, z_2)$  and  $(x_3, y_3, z_3)$  are three non-collinear points, then equation of the plane is

$$\begin{vmatrix} x - x_1 & y - y_1 & z - z_1 \\ x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ x_3 - x_1 & y_3 - y_1 & z_3 - z_1 \end{vmatrix} = 0$$

If above points are collinear, then

$x_1$	$y_1$	$z_1$
$x_2$	$y_2$	$z_2 = 0.$
$x_3$	<i>y</i> <sub>3</sub>	z <sub>3</sub>

**Equation of Plane in Intercept Form:** If a, b and c are x-intercept, y-intercept and z-intercept, respectively made by the plane on the coordinate axes, then equation of plane is x/a+y/b+z/c=1

# Equation of Plane Passing through the Line of Intersection of two given Planes

**Vector form:** If equation of the planes are  $\vec{r} \cdot n1 \rightarrow = d1$  and  $\vec{r} \cdot n2 \rightarrow = d2$ , then equation of any plane passing through the intersection of planes is

 $\vec{r} \cdot (n1 \rightarrow +\lambda n2 \rightarrow) = d1 + \lambda d2$ 

where,  $\lambda$  is a constant and calculated from given condition.

**Cartesian form:** If the equation of planes are  $a_1x + b_1y + c_1z = d_1$  and  $a_2x + b_2y + c_2z = d_2$ , then equation of any plane passing through the intersection of planes is  $a_1x + b_1y + c_1z - d_1 + \lambda (a_2x + b_2y + c_2z - d_2) = 0$ 

where,  $\boldsymbol{\lambda}$  is a constant and calculated from given condition.

### **Coplanarity of Two Lines**

**Vector form:** If two lines  $\vec{r} = a1 \rightarrow +\lambda b1 \rightarrow and \vec{r} = a2 \rightarrow +\mu b2 \rightarrow are coplanar, then$ 

 $(a2 \rightarrow -a1 \rightarrow) \cdot (b2 \rightarrow -b1 \rightarrow)=0$ 

Cartesian form If two lines 
$$\frac{x - x_1}{a_1} = \frac{y - y_1}{b_1} = \frac{z - z_1}{c_1}$$
 and  $\frac{x - x_2}{a_2} = \frac{y - y_2}{b_2} = \frac{z - z_2}{c_2}$  are coplanar, then  $\begin{vmatrix} x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix} = 0.$ 

#### Angle between Two Planes: Let $\theta$ be the angle between two planes.

**Vector form:** If  $n1 \rightarrow and n2 \rightarrow are normals to the planes and <math>\theta$  be the angle between the planes  $\vec{r} \cdot n1 \rightarrow = d1$  and  $\vec{r} \cdot n2 \rightarrow = d2$ , then  $\theta$  is the angle between the normals to the planes drawn from some common points.

$$\cos \theta = \frac{\begin{vmatrix} \overrightarrow{n_1} \cdot \overrightarrow{n_2} \\ \overrightarrow{n_1} & \overrightarrow{n_2} \end{vmatrix}}{\begin{vmatrix} \overrightarrow{n_1} & | & \overrightarrow{n_2} \end{vmatrix}}.$$

Note: The planes are perpendicular to each other, if  $n1 \rightarrow \cdot n2 \rightarrow =0$  and parallel, if  $n1 \rightarrow \cdot n2 \rightarrow =||n1 \rightarrow ||||n2 \rightarrow ||$ 

**Cartesian form:** If the two planes are  $a_1x + b_1y + c_1z = d_1$  and  $a_2x + b_2y + c_2z = d_2$ , then

$$\cos \theta = \frac{a_1 a_2 + b_1 b_2 + c_1 c_2}{\sqrt{a_1^2 + b_1^2 + c_1^2} \cdot \sqrt{a_2^2 + b_2^2 + c_2^2}}.$$

Note: Planes are perpendicular to each other, if  $a_1a_2 + b_1b_2 + c_1c_2 = 0$  and planes are parallel, if  $a_1a_2=b_1b_2=c_1c_2$ 

### Distance of a Point from a Plane

**Vector form:** The distance of a point whose position vector is a<sup>3</sup> from the plane

 $\vec{r} \cdot n^{=} dis |d-a \cdot n^{|}$ 

Note:

(i) If the equation of the plane is in the form  $\vec{r} \cdot \vec{n} = d$ , where  $\vec{n}$  is normal to the plane, then the perpendicular distance is  $||\vec{a} \cdot \vec{n} - d|||\vec{n}||$ (ii) The length of the perpendicular from origin O to the plane  $\vec{r} \cdot \vec{n} = dis|d||\vec{n}||$ :  $|\vec{a} = 0|$ 

**Cartesian form:** The distance of the point  $(x_1, y_1, z_1)$  from the plane Ax + By + Cz = D is

$$d = \frac{Ax_1 + By_1 + Cz_1 - D}{\sqrt{A^2 + B^2 + C^2}}$$

### Angle between a Line and a Plane

**Vector form:** If the equation of line is  $\vec{r} = \vec{a} + \lambda \vec{b}$  and the equation of plane is  $\vec{r} \cdot \vec{n} = d$ , then the angle  $\theta$  between the line and the normal to the plane is

$$\cos\theta = \frac{\overrightarrow{b} \cdot \overrightarrow{n}}{|\overrightarrow{b}| |\overrightarrow{n}|}$$

and so the angle  $\Phi$  between the line and the plane is given by 90° –  $\theta$ , i.e. sin(90° –  $\theta$ ) = cos  $\theta$ 

$$\sin\phi = \frac{\overrightarrow{b} \cdot \overrightarrow{n}}{|\overrightarrow{b}| |\overrightarrow{n}|}$$

**Cartesian form:** If a, b and c are the DR's of line and lx + my + nz + d = 0 be the equation of plane, then

$$\sin\theta = \frac{al + bm + cn}{\sqrt{a^2 + b^2 + c^2}\sqrt{l^2 + m^2 + n^2}}$$

If a line is parallel to the plane, then al + bm + cn = 0 and if line is perpendicular to the plane, then al=bm=cn

### **Remember Points**

(i) If a line is parallel to the plane, then normal to the plane is perpendicular to the line. i.e.  $a_1a_2 + b_1b_2 + c_1c_2 = 0$ 

(ii) If a line is perpendicular to the plane, then DR's of line are proportional to the normal of the plane.

### i.e. a1/a2=b1/b2=c1/c2

where,  $a_1$ ,  $b_1$  and  $c_1$  are the DR's of a line and  $a_2$ ,  $b_2$  and  $c_2$  are the DR's of normal to the plane.